

Modified TLH

DSP First, 2/e
Lecture Chapter 5
FIR Filtering Intro
Impulse response
PRESENTATION 2

SIGNALS USED TO CHARACTERIZE A SYSTEM

- Signals
 - ▶ Sinuoidal signals
 - ▶ Exponential signals
 - ▶ Complex exponential signals
 - ▶ Unit step and unit ramp
 - ▶ Impulse functions

SPECIAL INPUT SIGNALS

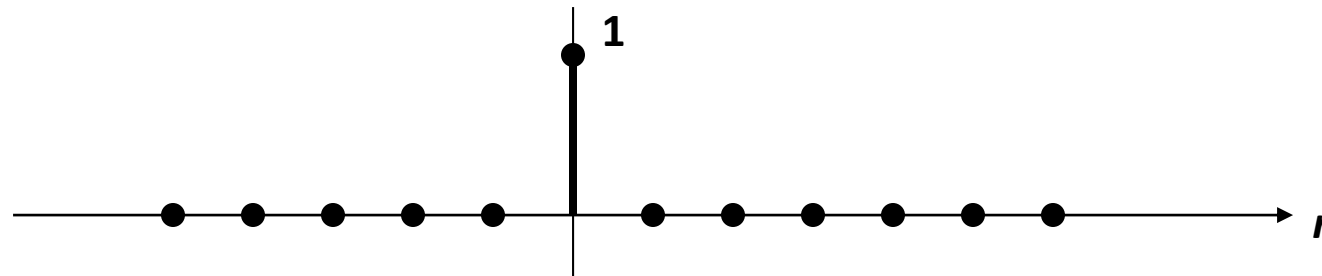
Another Test Signal

- $x[n] = \text{SINUSOID}$
- $x[n]$ has only one NON-ZERO VALUE

FREQUENCY RESPONSE (LATER)

$$\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$$

UNIT-IMPULSE



UNIT IMPULSE SIGNAL $\delta[n]$

n	...	-2	-1	0	1	2	3	4	5	6	...
$\delta[n]$	0	0	0	1	0	0	0	0	0	0	0
$\delta[n - 3]$	0	0	0	0	0	0	1	0	0	0	0

$\delta[n]$ is NON-ZERO
When its argument
is equal to ZERO

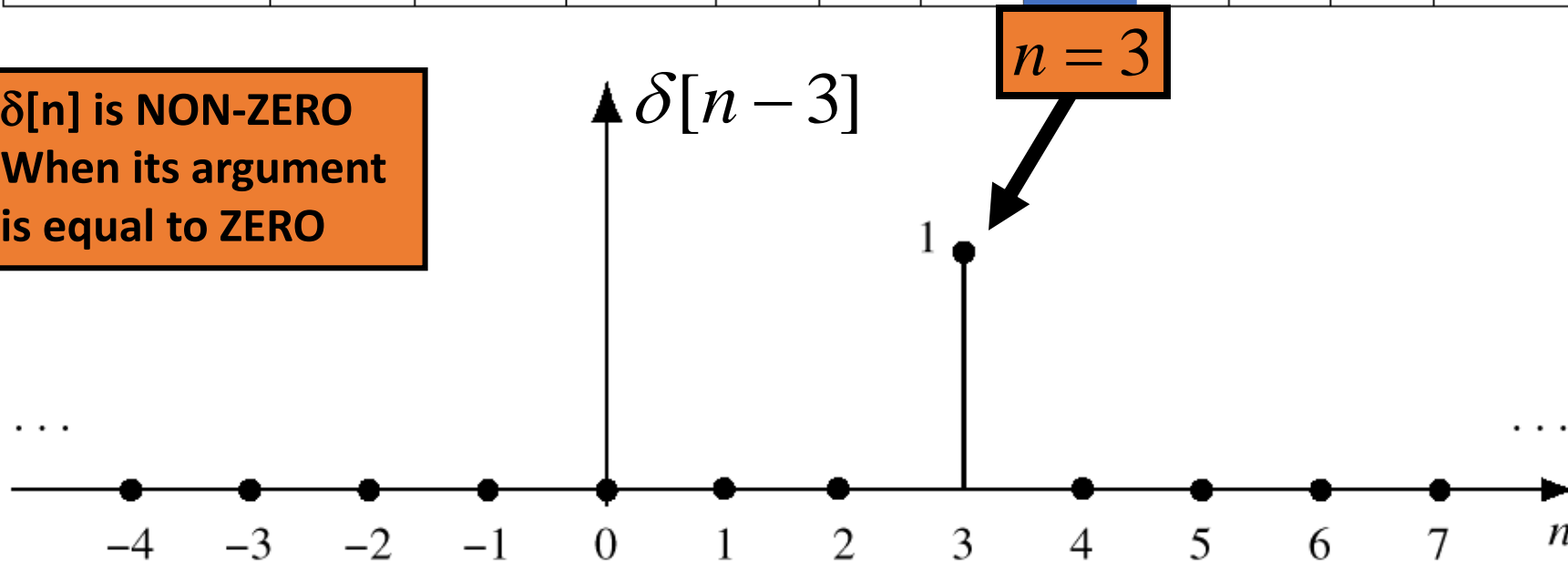
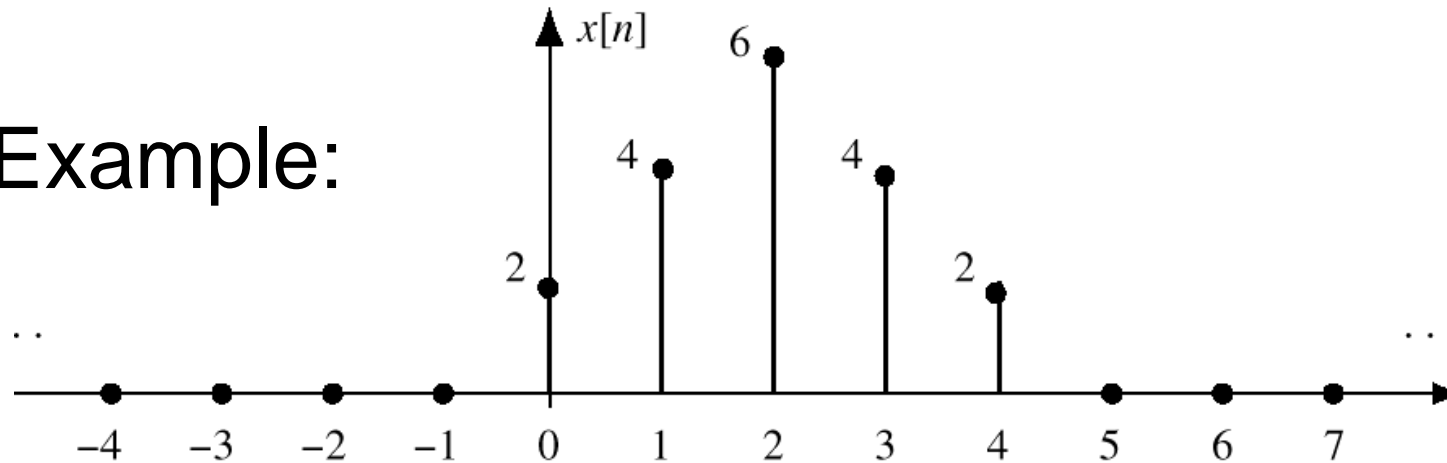


Figure 5.7 Shifted impulse sequence, $\delta[n - 3]$.

Sequence Representation TO GIVE MATHEMATICAL FORMULA FOR AMPLITUDE VALUES

Example:



$$x[n=0] = x[0] = 2$$

$$x[n=1] = x[1] = 4$$

JUST NUMBERS

$$x[n=2] = x[2] = 6$$

$$x[n=3] = x[3] = 4$$

$$x[n] = \cdots + \mathbf{0} \delta[n+1] + \mathbf{2} \delta[n] + \mathbf{4} \delta[n-1] \\ + \mathbf{6} \delta[n-2] + \mathbf{4} \delta[n-3] + \cdots$$

AN EQUATION

FIR IMPULSE RESPONSE

$h[n]$ CHARACTERIZES THE SYSTEM

$$y[n] = \sum_{k=0}^M b_k x[n-k]$$

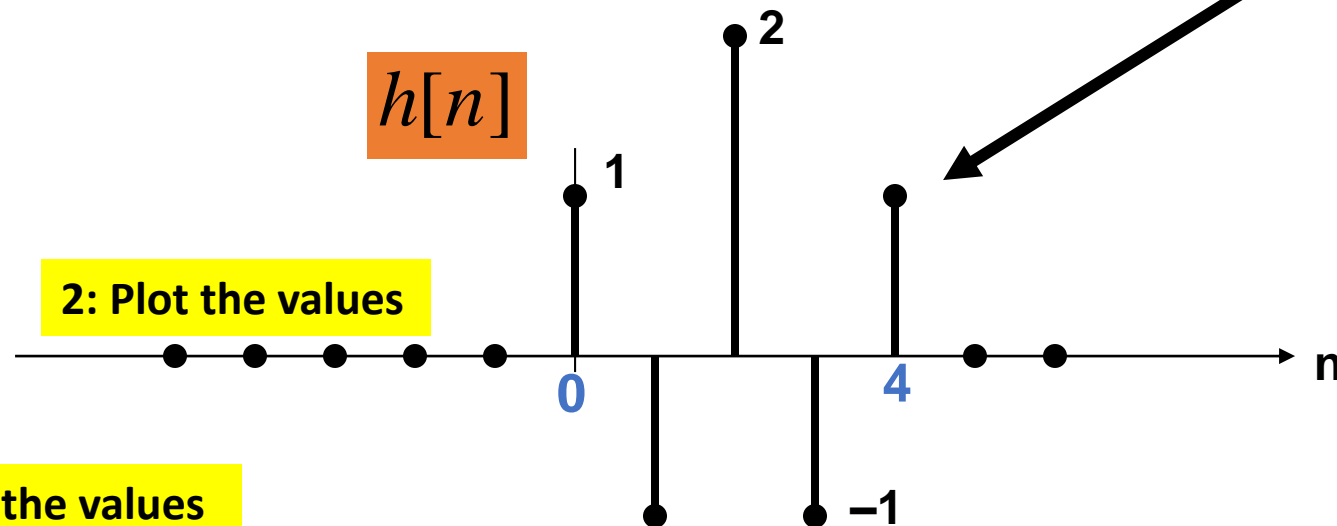
$$h[n] = \sum_{k=0}^M b_k \delta[n-k]$$

n	$n < 0$	0	1	2	3	...	M	$M + 1$	$n > M + 1$
$x[n] = \delta[n]$	0	1	0	0	0	0	0	0	0
$y[n] = h[n]$	0	b_0	b_1	b_2	b_3	...	b_M	0	0

3 Ways to Represent the FIR filter

1 Use **SHIFTED** IMPULSES to write $h[n]$

$$h[n] = \delta[n] - \delta[n-1] + 2\delta[n-2] - \delta[n-3] + \delta[n-4]$$



3: List the values

$$b_k = \{ 1, -1, 2, -1, 1 \}$$

True for any signal, $x[n]$

FILTERING EXAMPLE

- 7-point AVERAGER
 - Removes cosine
 - By making its amplitude (A) smaller

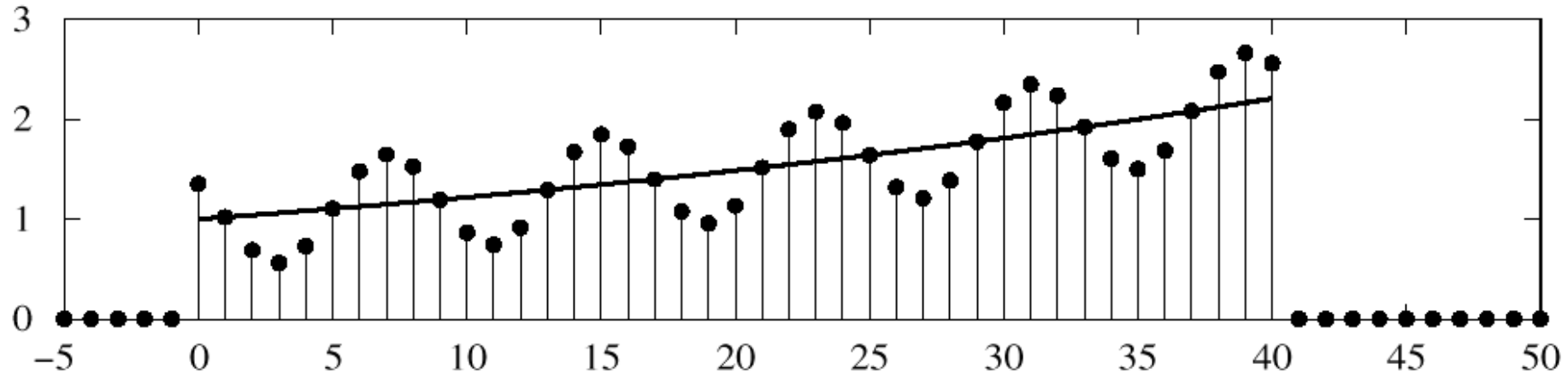
- 3-point AVERAGER
 - Changes A slightly

$$y_7[n] = \sum_{k=0}^6 \left(\frac{1}{7}\right) x[n-k]$$

$$y_3[n] = \sum_{k=0}^2 \left(\frac{1}{3}\right) x[n-k]$$

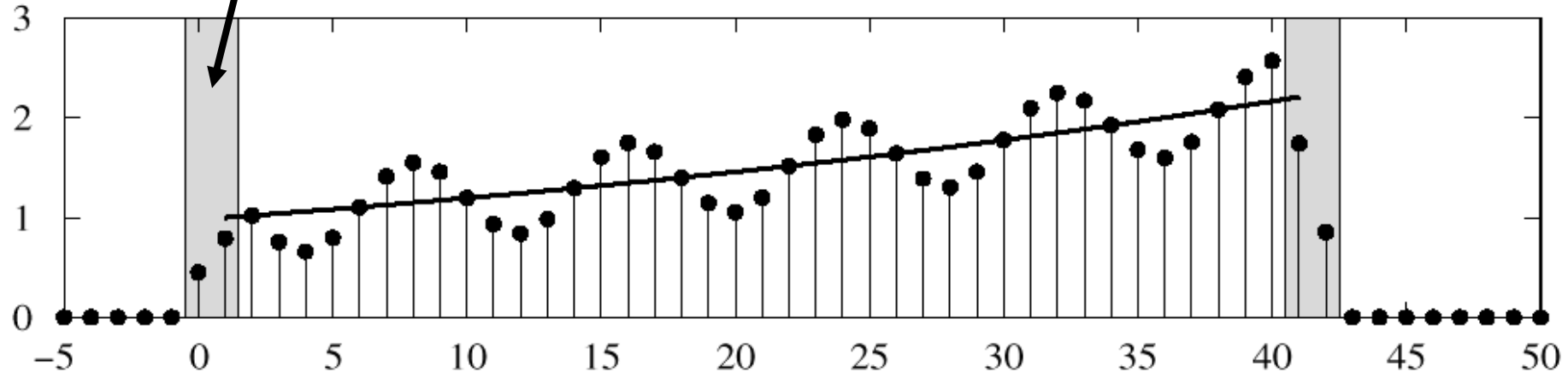
3-pt AVG EXAMPLE

Input : $x[n] = (1.02)^n + \cos(2\pi n/8 + \pi/4)$ for $0 \leq n \leq 40$



USE PAST VALUES

Output of 3-Point Running-Average Filter



7-pt FIR EXAMPLE (AVG)

Input : $x[n] = (1.02)^n + \cos(2\pi n/8 + \pi/4)$ for $0 \leq n \leq 40$

