

DSP FIRST

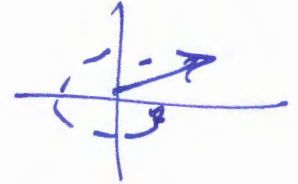
TLH EXAMPLES  
PROBLEMS

CH2  
CH2

1

COMBINE PGS 13-16

$\cos(\theta)$  or  $\sin(\theta)$   
PERIOD IS  $2\pi$  RADIANS



1. How long to rotate  $2\pi$  radians?  $T_0$

e.g.  $T_0 = 1$  sec  $\Rightarrow$  rotation  $2\pi$  rad/sec

$T_0 = \frac{1}{10}$  sec  $\Rightarrow$   $10 \times 2\pi$  rad/sec

So rotation =  $\frac{2\pi}{T_0}$  rad/sec

call this  $\omega = \frac{2\pi}{T_0}$

2. Since

$\theta$      $0 \longrightarrow 2\pi \longrightarrow 4\pi \longrightarrow \dots$   
 $t$      $0 \longrightarrow T_0 \longrightarrow 2T_0 \longrightarrow \dots$

number of cycles/sec =  $\frac{1}{T_0}$  = frequency  
in Hertz

So  $T_0 = 1$  s     $f = 1$  Hz

$T_0 = \frac{1}{10}$  s     $f = 10$  Hz

EG 2.4 Pg 16

3. So we can write

$$x(t) = A \cos(\omega_0 t) \quad \omega_0 = 2\pi f_0$$

with  $\omega_0 t = \theta$  and

$$2\pi f_0 t = \theta$$

$$2\pi \frac{t}{T_0} = \theta \quad \Rightarrow \quad \frac{t}{T_0} = \frac{\theta}{2\pi} \quad \text{Pg 18}$$

```

% Table of frequency and Period
clc,clear all
format rat % Fractions
frequency = [1 10 100 1000 10000 100000 ];
period = 1./[frequency];
% c = rdivide(a,b) and c = a./b perform right-array division
%by dividing each element of a by the corresponding element of b.
%If inputs a and b are not the same size,
%one of them must be a scalar value.
%
% One Way to do it - display and align
A=[frequency;period]'; % Make 2X6 Array
disp(' frequency-Hz period-Seconds')
disp(A)
% Better way Make a table
varNames={'Frequency','Period'}
T=table(frequency,period,'VariableNames',{'Frequency','Period'})

```

```

frequency-Hz  period-Seconds
           1                1
           10              1/10
           100             1/100
           1000            1/1000
           10000           1/10000
           100000          1/100000

```

```
varNames =
```

```
1x2 cell array
```

```
    {'Frequency'}    {'Period'}
```

```
T =
```

```
6x2 table
```

<i>Frequency</i>	<i>Period</i>
-----	-----
1	1
10	0.1
100	0.01
1000	0.001
10000	0.0001
1e+05	1e-05

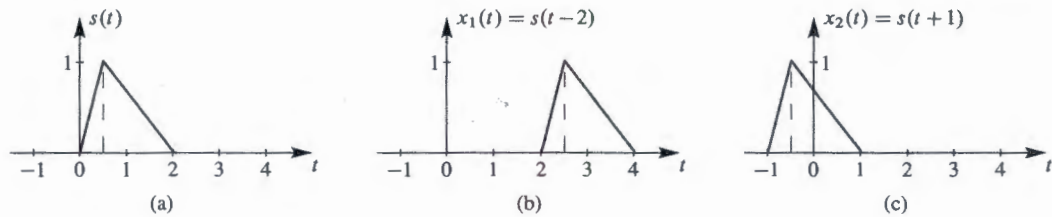


Figure 2-8 Illustration of time-shifting: (a) the triangular signal  $s(t)$ ; (b) shifted to the right by 2 s,  $x_1(t) = s(t - 2)$ ; (c) shifted to the left by 1 s,  $x_2(t) = s(t + 1)$ .

**EXERCISE 2.2**

Derive the equations for the shifted signal  $x_2(t) = s(t + 1)$ .

We will have many occasions to consider time-shifted signals. Whenever a signal can be expressed in the form  $x_1(t) = s(t - t_1)$ , we say that  $x_1(t)$  is a time-shifted version of  $s(t)$ . If  $t_1$  is a positive number, then the shift is to the right, and we say that the signal  $s(t)$  has been *delayed* in time. When  $t_1$  is a negative number, then the shift is to the left, and we say that the signal  $s(t)$  was *advanced* in time. In summary, time shifting is essentially a redefinition of the time origin of the signal. In general, any function of the form  $s(t - t_1)$  has its time origin moved to the location  $t = t_1$ .

Delay vs Advanced

For a sinusoid, the time shift is defined with respect to a zero-phase cosine that has a positive peak at  $t = 0$ . Since a sinusoid has many positive peaks, we must pick one to define the time shift, so we pick the positive peak of the sinusoid that is closest to  $t = 0$ . In the plot of Fig. 2-6, the time where this positive peak occurs is  $t_1 = 0.005$  s. Since the peak in this case occurs at a positive time (to the right of  $t = 0$ ), we say that the time shift is a delay of the zero-phase cosine signal. Now we can relate the time delay to phase. Let  $x_0(t) = A \cos(\omega_0 t)$  denote a cosine signal with zero phase. A delay of  $x_0(t)$  can be converted to a phase  $\varphi$  by making the following comparison:

XX

$$x_0(t - t_1) = A \cos(\omega_0(t - t_1)) = A \cos(\omega_0 t + \varphi)$$

$$\Rightarrow \cos(\omega_0 t - \omega_0 t_1) = \cos(\omega_0 t + \varphi)$$

WATCH SIGN!

Since the second equation must hold for all  $t$ , we conclude that  $\varphi = -\omega_0 t_1$ . Notice that the phase is negative when the time shift  $t_1$  is positive (a delay). We can also express the phase in terms of the period ( $T_0 = 1/f_0$ ) where we get the more intuitive formula

$$\varphi = -\omega_0 t_1 = -2\pi \left( \frac{t_1}{T_0} \right) \tag{2.7a}$$

which states that the phase is  $2\pi$  times the fraction of a period given by the ratio of the time shift to the period. If we need to get the time shift from the phase, we solve for  $t_1$

$$t_1 = -\frac{\varphi}{\omega_0} = -\frac{\varphi}{2\pi f_0} = -\frac{\varphi T_0}{2\pi} \tag{2.7b}$$

Since the positive peak nearest to  $t = 0$  must always lie within the interval  $[-\frac{1}{2}T_0, \frac{1}{2}T_0]$ , the phase calculated in (2.7a) will always satisfy  $-\pi < \varphi \leq \pi$ . However,

Time and Phase  
See YouTube  
Timothy schulz  
Intro to The Sinusoid



DEMO  
Sine Drill

\*

!!

YouTube DSP First Pg  
 Timothy Scholz Intro to the sinusoidal signal  
 $S(t) = A \cos(2\pi f t + \phi)$

(2)  
Pg 14  
11:15

$$= A \cos \left[ 2\pi f \left( t - \frac{\phi}{2\pi f} \right) \right]$$

Looks like 0 phase with delay  $-\frac{\phi}{2\pi f}$

$\phi$  radians / delay seconds in seconds



see Page 13 sine/cosine

So 1 cycle =  $2\pi$  radians  
 =  $T$  seconds = Period  
 =  $1/f$  cycles/second = frequency

So  $\frac{\phi}{2\pi} = \frac{t_{\text{delay}}}{T}$  to the right i.e. + time

Example:  $2\pi$  rad;  $1/f$  period; shift in +t

Shift for  $A \cos(2\pi f t - \phi) = A \cos[\omega(t - t_d)]$

Here  $f = 1 \text{ Hz}$  so  $T = 1 \text{ sec}$

$\phi$ shift	$t_{\text{delay}} = \frac{\phi}{2\pi} \times T$
$\pi/4$	$\frac{\pi/4}{2\pi} \cdot 1 = 1/8 \text{ sec}$ check $\frac{1}{8} \cdot 2\pi = \pi/4$ ✓
$\pi/2$	$\frac{\pi/2}{2\pi} \cdot 1 = 1/4 \text{ sec} \Rightarrow A \cos[2\pi(t - 1/4)]$
$\pi$	$1/2$
$\vdots$	

Page 15 Figure 2.6

PROBLEM 2

$$\frac{t}{25\text{ms}} = \frac{-0.4\pi}{2\pi} = -0.2$$

Shift Right

$$t = -0.2(25\text{ms}) = \underline{5.0\text{ms}}$$

$$\underline{f(t) = \cos(2\pi 40t - 0.4\pi)}$$

Note peak at zero

$$2\pi 40 t - 0.4\pi = 0$$

$$\text{Positive shift } t = \frac{0.4\pi}{2\pi 40} = \frac{0.4}{2 \times 40} = \frac{0.2}{40} = 0.2(25\text{ms}) = \underline{5.0\text{ms}}$$

Fig 2.1 Pg 10

$$10 \cos(2\pi 440t - 0.4\pi)$$

$$\text{So } t = \frac{0.4\pi}{2\pi 440} = \frac{0.2}{440} = \underline{0.2(2.27\text{ms})} = \underline{0.454\text{ms}}$$

For phase learn

cos/sin

00  
45  
60  
90  
120  
150  
180  
210  
240  
270  
300  
315  
330  
345  
360

so we define the phase to be  $\varphi = \varphi' - \pi/2$  in (2.2). For simplicity and to prevent confusion, we often avoid using the sine function.

- (c)  $\omega_0$  is called the **radian frequency**. Since the argument of the cosine function must be in radians, which is dimensionless, the quantity  $\omega_0 t$  must likewise be dimensionless. Thus,  $\omega_0$  must have units of rad/s if  $t$  has units of seconds. Similarly,  $f_0 = \omega_0/2\pi$  is called the **cyclic frequency**, and  $f_0$  must have units of  $s^{-1}$ , or hertz.

**EXAMPLE 2-1 Plotting Sinusoids**

Figure 2-6 shows a plot of the signal

$$x(t) = 20 \cos(2\pi(40)t - 0.4\pi) \quad (2.3)$$

In terms of our definitions, the signal parameters are  $A = 20$ ,  $\omega_0 = 2\pi(40)$  rad/s,  $f_0 = 40$  Hz, and  $\varphi = -0.4\pi$  rad. The signal size depends on the amplitude parameter  $A$ ; its maximum and minimum values are  $+20$  and  $-20$ , respectively. In Fig. 2-6 the maxima occur at

$$t = \dots, -0.02, 0.005, 0.03, \dots$$

and the minima at

$$\dots, -0.0325, -0.0075, 0.0175, \dots$$

The time interval between successive maxima in Fig. 2-6 is 0.025 s, which is equal to  $1/f_0$ . To understand why the signal has these properties, we will need to do more analysis.

$T = \frac{1}{40} \text{ sec}$   
 $= 25 \text{ ms}$



**DEMO**  
Sinusoids

**2-3.1 Relation of Frequency to Period**

Repeats  $2\pi$  radians

PERIOD

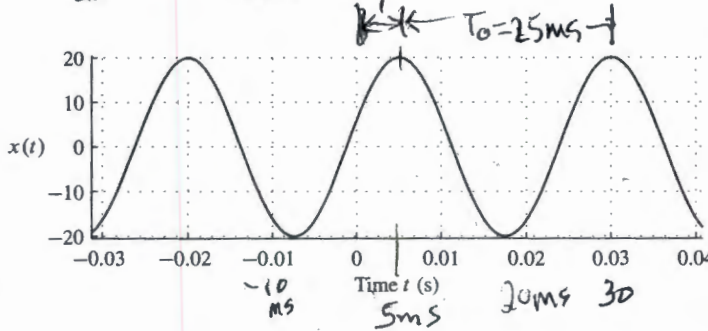
The sinusoid plotted in Fig. 2-6 is a periodic signal. The **period** of the sinusoid, denoted by  $T_0$ , is the time duration of one cycle of the sinusoid. In general, the frequency of the sinusoid determines its period, and the relationship can be found by applying the definition of periodicity  $x(t + T_0) = x(t)$  as follows:

$\omega_0 = 40 \text{ r/s} = \frac{2\pi}{T_0} = \frac{1}{25 \text{ ms}}$

$$A \cos(\omega_0(t + T_0) + \varphi) = A \cos(\omega_0 t + \varphi)$$

$$\cos(\omega_0 t + \underbrace{\omega_0 T_0}_{=2\pi} + \varphi) = \cos(\omega_0 t + \varphi)$$

Van Veen  
video  
periodic



$t = \frac{-0.4\pi}{2\pi} = -0.2$   
 $t = 5 \text{ ms}$   
 $T_0 \text{ right}$   
 $2\pi f_0 T_0 = 2\pi$   
 $T_0 = 1/f_0$   
See Fig 2.1

**Figure 2-6** Sinusoidal signal with parameters  $A = 20$ ,  $\omega_0 = 2\pi(40)$ ,  $f_0 = 40$  Hz, and  $\varphi = -0.4\pi$  rad.

$T_0 = \frac{1}{40 \text{ Hz}} = 25$

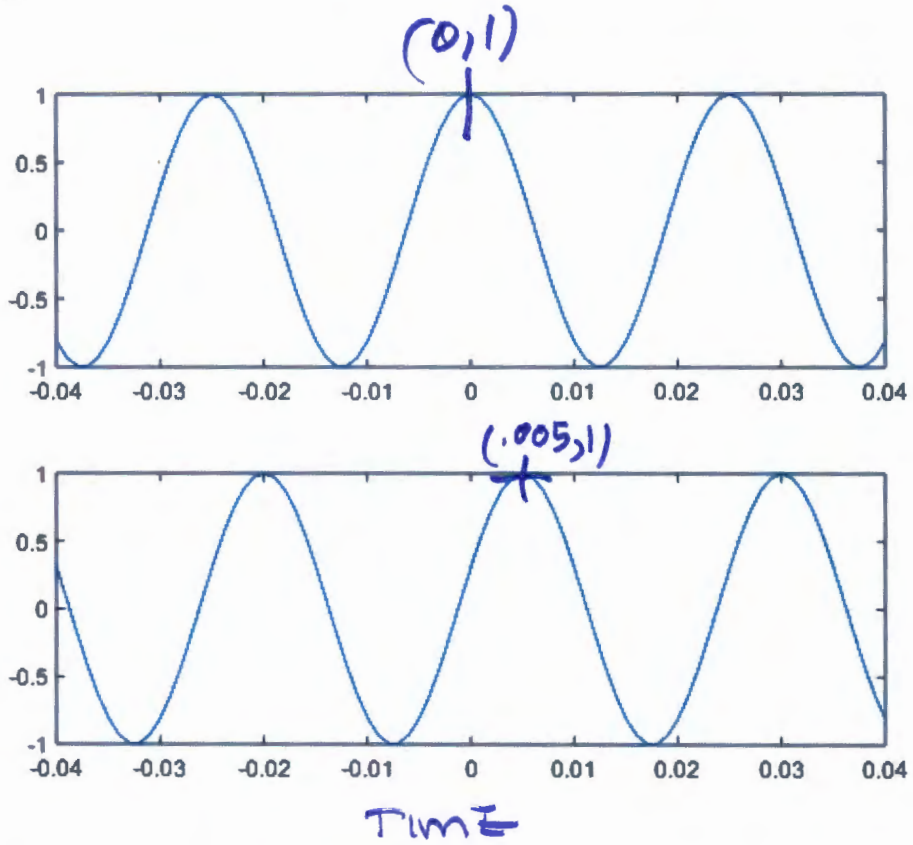
See Page 24 F 2.11  
For  $e^{j(\omega_0 t + \varphi)}$

```

% Plot of cosine and shifted cosine
% 20*cosine(2*pi*40 -0.4*pi) vs 20*cosine(2*pi*40)
% T0= 1/40 = 25ms. Consider a time axis from -.04 to +.04 seconds
taxis = -.04:.001:.04;
x1=cos(2*pi*40*taxis) ;
x2=cos(2*pi*40*taxis -0.4*pi);
subplot(2,1,1); plot(taxis,x1)
subplot(2,1,2); plot(taxis,x2)
grid on

```

FIG 2-0



Published with MATLAB® R2018a

# LABELS USING FIGURE TOOLS

