## Corrections to Thomas L. Harman, Advanced Engineering Mathematics with MATLAB- Page 1/4

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This is a summary of the corrections to the second edition.

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Page xiv Correct Web site in preface: Change www.brookscole.com ... to

http://www.cengagebrain.com/shop/index.html

Then enter ISBN number 0-534-37164 and Go to "Free Studey Tools - Access

Page xvi Correct my e-mail in preface- replace harman@cl.uh.edu with harman@uhcl.edu

Page 57 at top Angle is  $5\pi/4 + \pi/4 = 3\pi/2$  but principal angle is  $-\pi/2$ . angle((-1-i)\*(1+i)) = -1.5708 =  $-\pi/2$ (-1-i)\*(1+i) ans = 0.0000 - 2.0000i

Page 183 - Add the I after  $a_0$ .

then the matrix equation is

$$A^{n} + a_{n-1}A^{n-1} + \dots + a_{1}A + a_{0}I = 0.$$

## Corrections to Advanced Engineering Mathematics with MATLAB- 2nd Page 2

Page 185 - Change  $\lambda_1$  to  $\lambda_2$  in the second line of Equation 4.54; change  $\lambda_1$  to  $\lambda_n$  in the last line of Equation 4.54.

$$f(\lambda_1) = \beta_{n-1}\lambda_1^{n-1} + \dots + \beta_1\lambda_1 + \beta_0,$$
  

$$f(\lambda_2) = \beta_{n-1}\lambda_2^{n-1} + \dots + \beta_1\lambda_2 + \beta_0,$$
  

$$\vdots$$
  

$$f(\lambda_n) = \beta_{n-1}\lambda_n^{n-1} + \dots + \beta_1\lambda_n + \beta_0.$$
(1)

Page 196, Figure 4.4:  $m_1$  in the cart on the right should be  $m_2$ 

## Corrections to Advanced Engineering Mathematics with MATLAB- 2nd Page 3

Page 210 - In Theorem 5.2, third line, separate the a and b in brackets ... with continuous coefficients in the interval  $[a \ b]$ . Then, ...

Page 214 - In Example 5.2, change the t = 1.1 to t = 1.005 in the next to last line

 $\dots$  selected to start at t = 1.005 so that the infinite  $\dots$ 

Page 215 - there is an error in the Figure 5.1: (2,20) should be (2,-10)

Page 238 Equation 5.65 should read

$$\mathbf{x}(\mathbf{t}) = \mathbf{e}^{\mathbf{A}\mathbf{t}}\mathbf{x}_{\mathbf{0}} = \mathbf{M}\mathbf{e}^{\mathbf{\Lambda}}\mathbf{M}^{-1}\mathbf{x}_{\mathbf{0}},$$

Page 247 Table 5.4 (The sign is wrong in the equation for  $\dot{\mathbf{x}_p}(t)$ ). The function in column 2 should be:

$$\dot{\mathbf{x}}_p(t) = A\mathbf{x}_p(t) - \mathbf{f}(t).$$

Page 259 MATLAB Script comment should read

```
D2y+2*z*Wn*Dy+Wn^2*y=9.81*U(t)
```

Page 281 Shift the text in the MATLAB script over to the left - some text is cut off.

Page 287

$$\lim_{n \to \infty} \left| \frac{a_{n+1}}{a_n} \right| \quad \text{not} \quad \lim_{n \to \infty} \left| \frac{a^{n+1}}{a_n} \right|.$$
$$\lim_{n \to \infty} \left| \frac{a_{n+1}}{a_n} \right| = \lim_{n \to \infty} \left| \frac{2}{n+1} \right| = 0.$$

Page 299 last line: Replace "disk" with "Web site"

... using the MATLAB M-file EX6\_7.M on our Web site leads to the following results:

Page 323 Example 6.14 first line: Replace "constant" with "nonconstant" ... differential equation with nonconstant coefficients

Page 407 in MATLAB program Example 8.14 Correct transform of system

 $H = 1./(sqrt(w.^4 + 5*w.^2 + 4))$ 

## Corrections to Advanced Engineering Mathematics with MATLAB- 2nd Page 4

Page 430 in Example 9.5: add the factor  $e^{-t}$ 

$$y(t) = \frac{1}{2} + \frac{1}{2}\sqrt{2}\cos\left(t + \frac{\pi}{4}\right)e^{-t}.$$

Page 484 Equation 10.47 Suppose that  $\mathcal{Z}[f(n)] = F(z)$ , then

$$\mathcal{Z}[f(n+N)] = z^N F(z) - f(0) z^N - f(1) z^{N-1} - \dots - f(N-1) z^N$$

Page 505; Replace y(z)/z with Y(z)/zAnalytically, Y(z)/z could be written in terms ...

Page 527. The resolution is 1 Hertz (not 2 Hz) since

Tperiod = N Ts = 1 second so that  $\Delta f = 1$  Hz

Page 532 Line after Equation 11.15: Replace n with N. where p takes the values  $0, 1, \ldots, N - 1$ .

Page 544 $W_8^6$  not  $W_6^6$