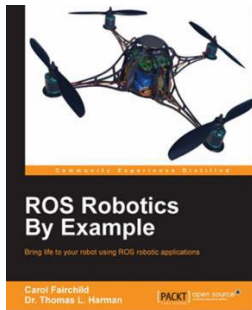


ROS Update and Git 10/11/2018

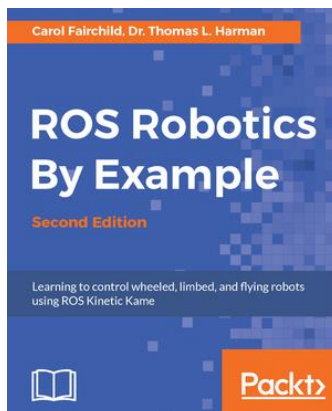
Chapter 1 *ROS Robotics By Example 1st Edition Indigo*

<https://www.packtpub.com/hardware-and-creative/ros-robotics-example>



Chapter 1 *ROS Robotics By Example 2nd Edition Kinetic*

<https://www.packtpub.com/hardware-and-creative/ros-robotics-example-second-edition>



Github – the Code:

<https://github.com/FairchildC/ROS-Robotics-By-Example-2nd-Edition>

ROS WATCH THESE

Tully Foote Published on Aug 26, 2013

Tully Foote describes why they created ROS, new ROS initiatives as well as describes his participation in the DARPA challenges and shows an affordable personal robot - Turtlebot - that uses Microsoft Kinect and utilizes ROS for its basic functions.

<https://www.youtube.com/watch?v=xCiOY9Vplek>

UPDATE FOR ROS

<http://spectrum.ieee.org/automaton/robotics/robotics-software/ros-robot-operating-system-celebrates-8-years>

By Brian Gerkey Posted 9 Dec 2015 | 23:35 GMT

GIT Git is an open-source version control system that was started by Linus Trovalds – the same person who created Linux.

<http://www.howtogeek.com/180167/htg-explains-what-is-github-and-what-do-geeks-use-it-for/>

<http://git-scm.com/book/en/v1/Getting-Started>

<http://git-scm.com/book/en/v1/Git-Basics>