## **Turtlesim References 9/2018**

# 1. ROS Robotics By Example 2<sup>nd</sup> Edition, Fairchild and Harman, ISBN 978-1-78847-959-2

Chapter 1, Chapter 8 (Pg 360-366; Joystick Control)

https://www.packtpub.com/hardware-and-creative/ros-robotics-example-second-edition

#### 2. Turtlesim Guide and Cheat Sheet on the class website

http://sceweb.sce.uhcl.edu/harman/courses.htm

3. Turtlesim is a tool made for teaching ROS and ROS packages. Ros wiki

http://wiki.ros.org/turtlesim

4. This is the real deal from the turtle's (Tulle's Mouth) Advanced with videos

http://wiki.ros.org/turtlesim/Tutorials

#### 5. Here are a few Video examples – surf YouTube for many other videos.



3a. ROS Assignment For Turtlesim 5 videos Anusna Chakraborty

Published on Aug 25, 2017 **1 - Video 1 9:52** <u>https://www.youtube.com/watch?v=83kbOIMQ3d8&app=desktop</u> <u>https://www.youtube.com/watch?v=X0zvG6v5-go</u> Video 2:7:57 Python

https://www.youtube.com/watch?v=BVzKJ-Ui8M0 Video 3 7:43

3b. Anis Koubaa Various Videos – These with Turtlesim. He is editor of the "big" book

Robot Operating System Volume 1 http://www.springer.com/gp/book/9783319260525

(728 pages) and Volume 2

# [CS460] ROS Tutorial 2: Understanding ROS Topics, Node and Messages

https://www.youtube.com/watch?v=Yx\_vGAt74sk&feature=youtu.be

## [CS460] ROS Tutorial 3: ROS Publishers and Subscribers in C++ and Python

https://www.youtube.com/watch?v=8bUkLNEu5Ns

If you look at Tutorial 4: GitHub - zshn25/turtlesim\_cleaner: This is the code from youtube ROS ... <u>https://github.com/zshn25/turtlesim\_cleaner</u>

turtlesim\_cleaner - This is the code from **youtube ROS** Tutorial 4 Series. ... This tutorial demonstrates how to develop a simple cleaning application with **turtlesim** 

Look at src to see C++ code for the turtlesim.