

Project Examples Fall 2015 and Spring 2016

Robotics

Baxter Program for Application – pick and place of Colored Golf Balls – Sort the balls according to color.

**Turtlebot Mobile Robot Obstacle Avoidance
 Use with Kinect for depth and vision
 Moving Object Following (Based on Kinect)**

Robot Apps and Software – ROS Networking for TurtleBot using Ad-hoc network